

Some contributions to the analysis of piecewise linear systems

PhD thesis

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Ddays Murcia, October 3-5, 2018.



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 - Motivation

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 - Motivation
 - Main contributions

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 - Application to discontinuous 3D PWL models

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 - Cubic Memristor Oscillator

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Fundamental elements

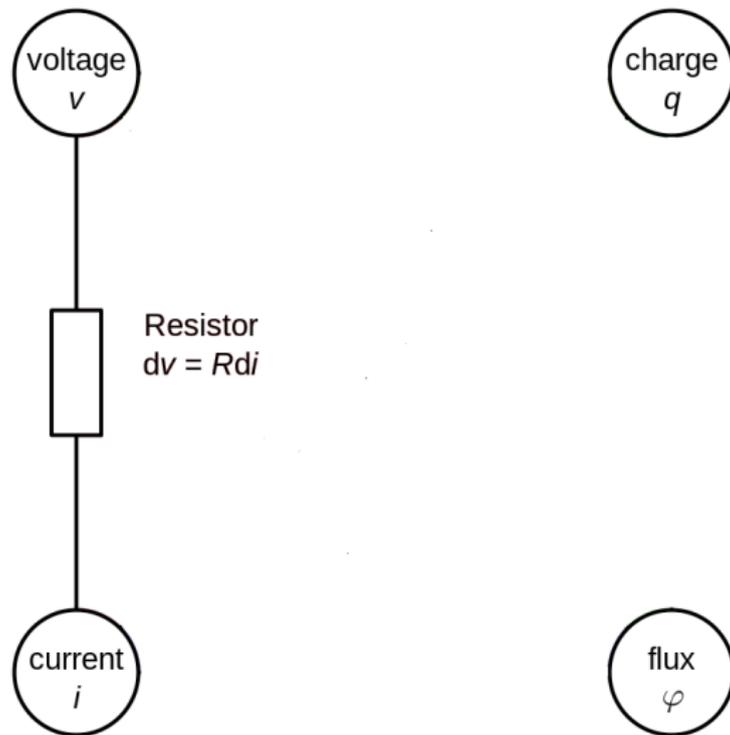
voltage
 v

charge
 q

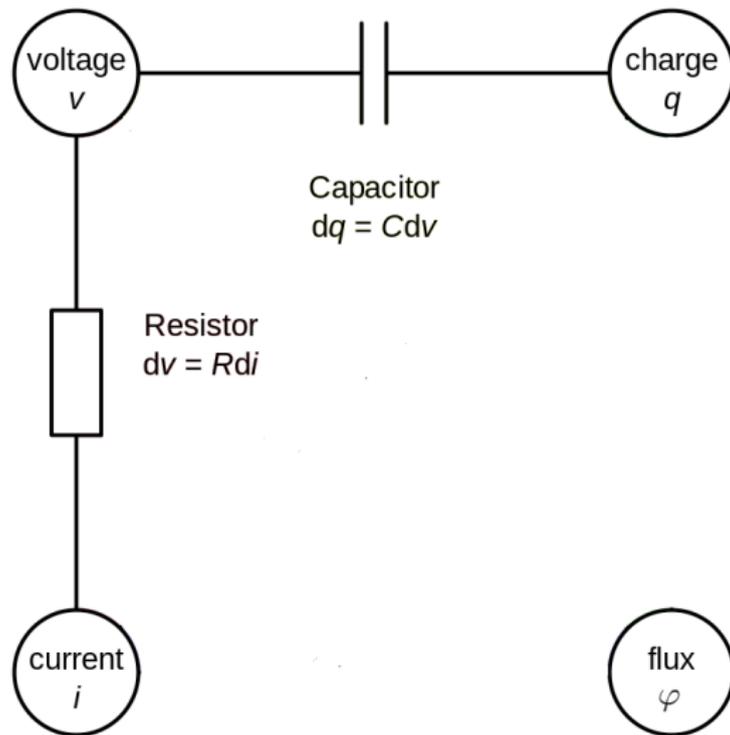
current
 i

flux
 φ

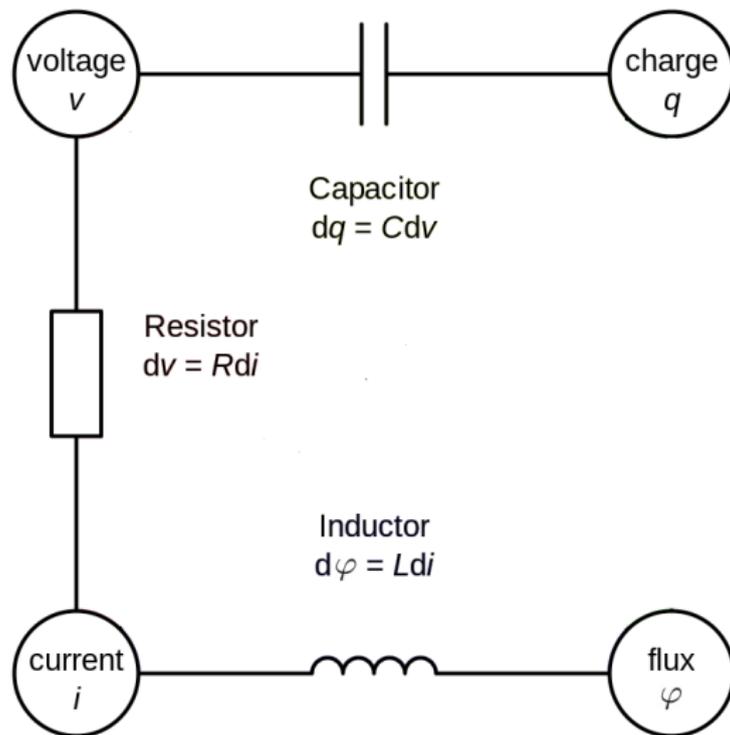
Fundamental elements



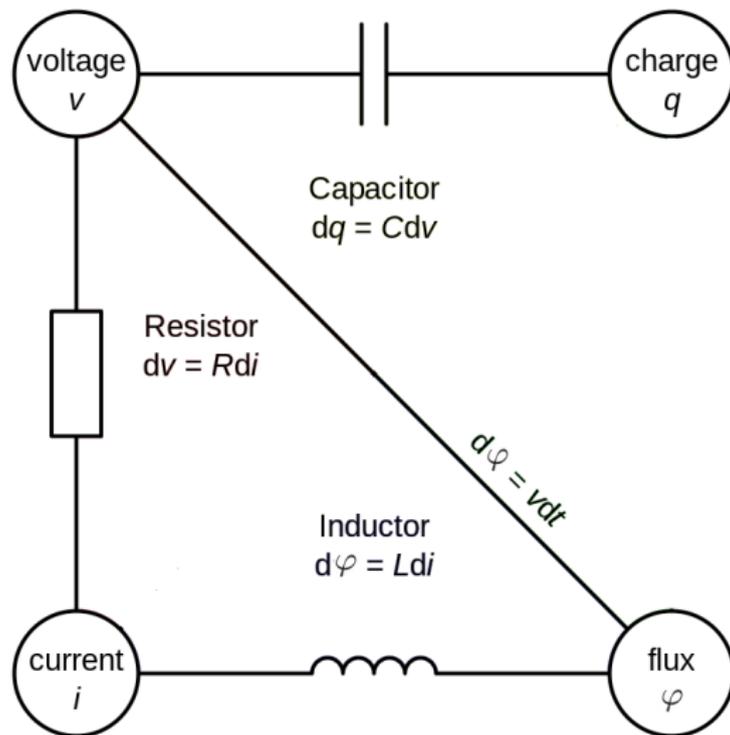
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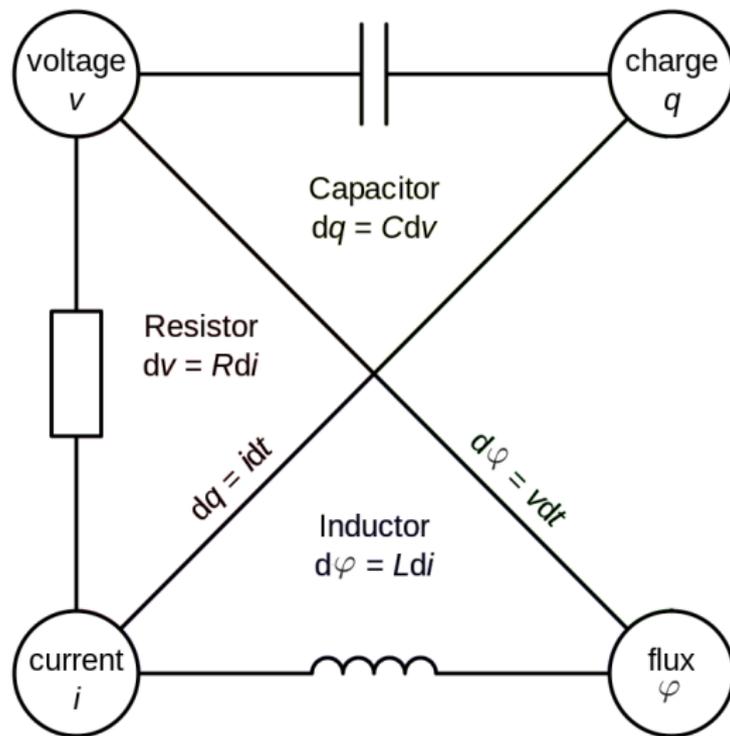
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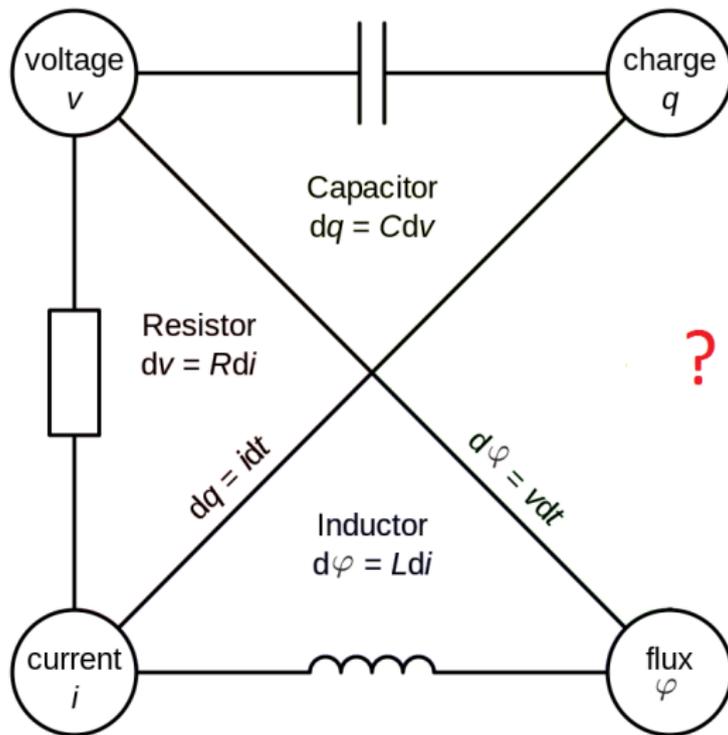


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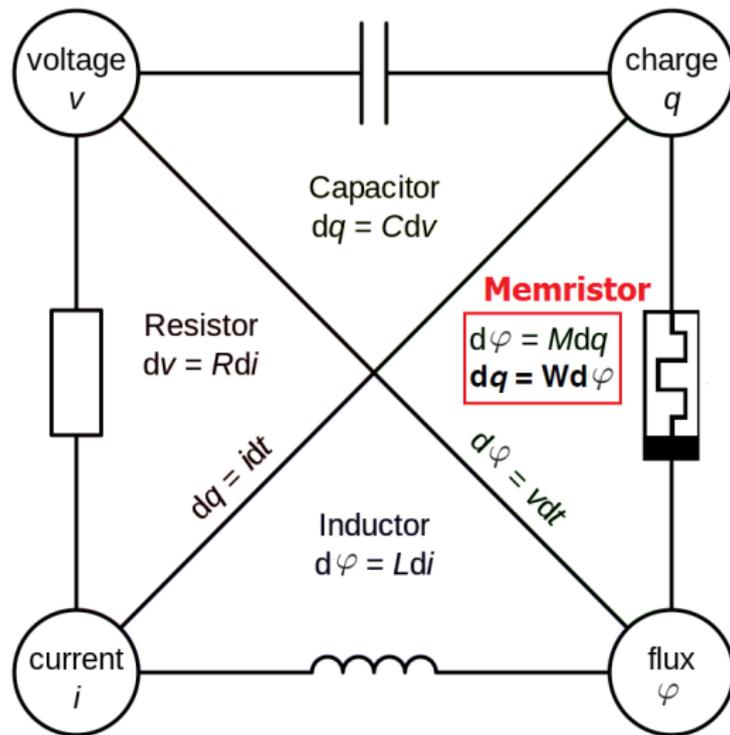


Fundamental elements





Memory resistor [Chua, 1971]



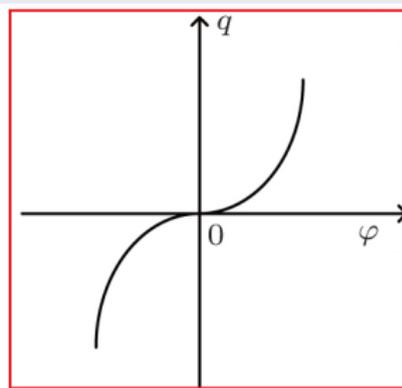
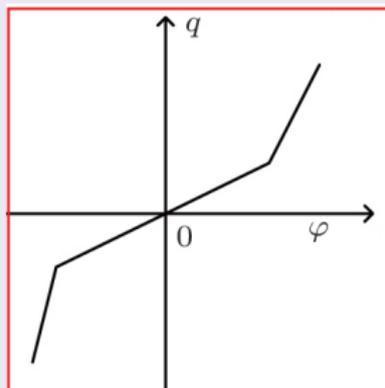
Definition ([Chua, 1971])

A memristor is a passive two-terminal electronic device, characterized by a nonlinear constitutive relation between the flux ϕ and the charge q .

Memristor constitutive relation

Definition ([Chua, 1971])

A memristor is a passive two-terminal electronic device, characterized by a nonlinear constitutive relation between the flux ϕ and the charge q .



The first memristor

The **missing memristor found**

[DB Strukov](#), [GS Snider](#), [DR Stewart](#), [RS Williams](#) - nature, 2008 - nature.com

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nature

Vol 453 | 1 May 2008 | doi:10.1038/nature06932

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The missing memristor found

Dmitri B. Strukov¹, Gregory S. Snider¹, Duncan R. Stewart¹ & R. Stanley Williams¹



Memristor oscillators

M Itoh, LO Chua - International Journal of Bifurcation and Chaos, 2008 - World Scientific

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MEMRISTOR OSCILLATORS

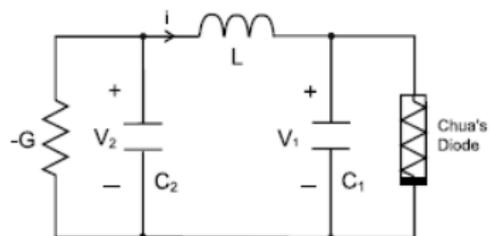
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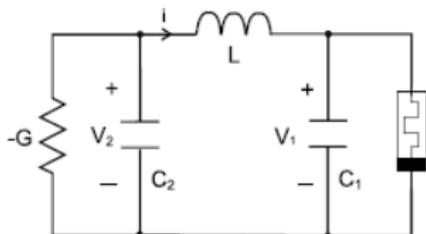
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*Department of Electrical Engineering and Computer Sciences,
University of California, Berkeley,
Berkeley, CA 94720, USA*

3D memristor



3D memristor

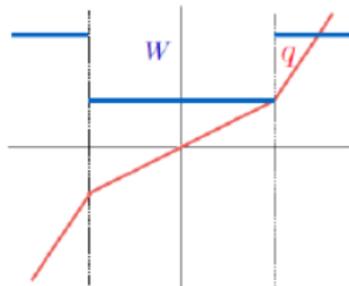


$$\frac{dx}{d\tau} = \alpha(y - W(z)x),$$

$$\frac{dy}{d\tau} = -\xi x + \beta y,$$

$$\frac{dz}{d\tau} = x,$$

$$\alpha = \frac{1}{C}, \quad \xi = \frac{1}{L}, \quad \beta = \frac{R}{L},$$



$$W(z) = \begin{cases} b, & \text{if } |z| > 1, \\ a, & \text{if } |z| \leq 1, \end{cases}$$

$$q(z) = \begin{cases} b(z-1) + a, & \text{if } z > 1, \\ az, & \text{if } |z| \leq 1, \\ b(z+1) - a, & \text{if } z < -1, \end{cases}$$

Two periodic attractors

$$\alpha = 1, \beta = 0.1, \gamma = 1, a = 0.02, b = 2$$

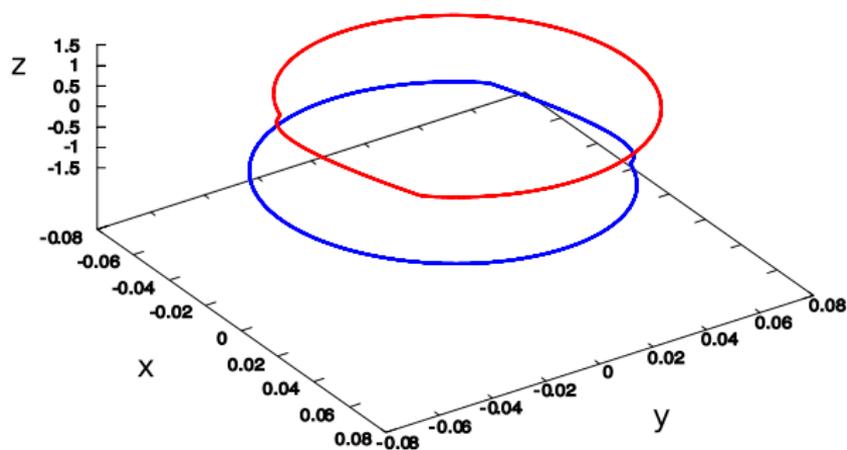
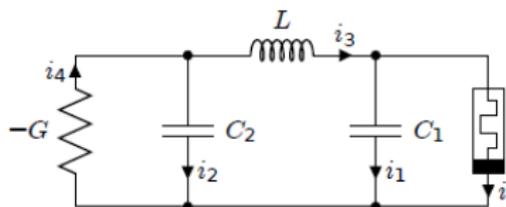


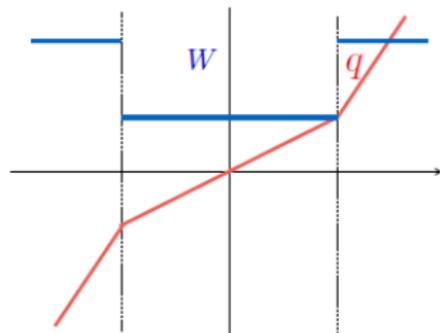
Figure: Two periodic attractors, [Itoh and Chua, 2008]

4D PWL memristor



$$\begin{aligned}\frac{dx}{d\tau} &= \alpha y - \alpha W(w)x, \\ \frac{dy}{d\tau} &= z - x, \\ \frac{dz}{d\tau} &= -\beta y + \gamma z, \\ \frac{dw}{d\tau} &= x,\end{aligned}$$

$$\alpha = \frac{1}{C_1}, \quad \beta = \frac{1}{C_2}, \quad \gamma = \frac{G}{C_2}, \quad L = 1$$



Chaotic attractor

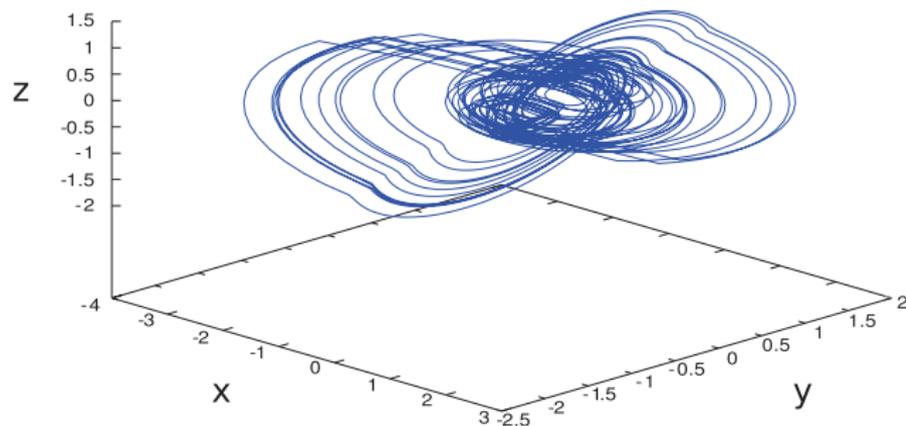


Figure: Chaotic attractor, [Itoh and Chua, 2008]

[Messias et al., 2010] and [Scarabello and Messias, 2014]

International Journal of Bifurcation and Chaos, Vol. 20, No. 2 (2010) 437–450

HOPF BIFURCATION FROM LINES OF EQUILIBRIA WITHOUT PARAMETERS IN MEMRISTOR OSCILLATORS

MARCELO MESSIAS*, CRISTIANE NESPOLI†
and VANESSA A. BOTTA‡

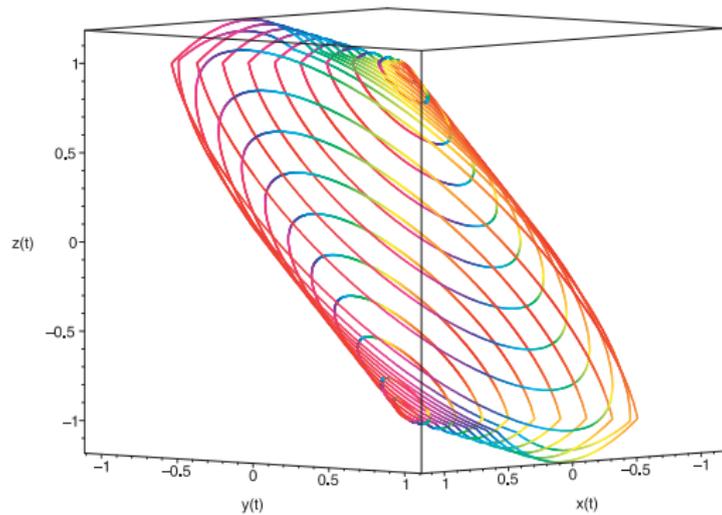
International Journal of Bifurcation and Chaos, Vol. 24, No. 1 (2014) 1430001 (18 pages)

Bifurcations Leading to Nonlinear Oscillations in a 3D Piecewise Linear Memristor Oscillator

Marluce da Cruz Scarabello* and Marcelo Messias†

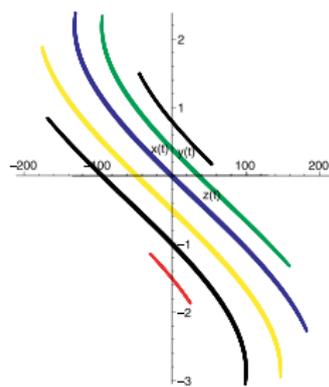
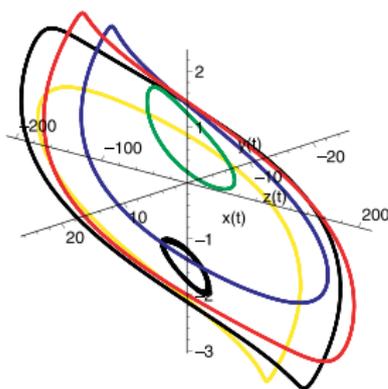


3D PWL memristor oscillator



Cubic memristor

$$q(z) = z^3 + az^2 + bz + c, \quad a^2 - 3b \leq 0$$



Extreme multistability

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[B.C. Bao](#), [Q. Xu](#), H. Bao, M. Chen - Electronics Letters, 2016 - IET

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[B.C. Bao](#), H. Bao, [N. Wang](#), M. Chen, [Q. Xu](#) - Chaos, Solitons & Fractals, 2017 - Elsevier

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[B. Bao](#), T. Jiang, G. Wang, P. Jin, H. Bao, M. Chen - Nonlinear Dynamics, 2017 - Springer

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The tree-dimensional model

We consider a family of 3D systems, which is general enough to capture all the mathematical models of memristor oscillators.

$$\begin{aligned}\dot{x} &= a_{11}W(z)x + a_{12}y, \\ \dot{y} &= a_{21}x + a_{22}y, \\ \dot{z} &= x,\end{aligned}\tag{1}$$

where the constants $a_{11}, a_{12}, a_{21}, a_{22} \in \mathbb{R}$, the function W is defined by

$$W(z) = \frac{dq(z)}{dz},\tag{2}$$

and q is a continuous function.

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$$W(z) = \frac{dq(z)}{dz},\tag{2}$$

and q is a continuous function.

The equilibrium points of system (1) are given by

$$E = \{(x, y, z) \in \mathbb{R}^3 : x = y = 0 \text{ and } z \in \mathbb{R}\}.\tag{3}$$

Theorem

Consider system (1) where the function W is defined as in (2). For any $h \in \mathbb{R}$, the set

$$S_h = \{(x, y, z) \in \mathbb{R}^3 : -a_{22}x + a_{12}y - a_{12}a_{21}z + a_{11}a_{22}q(z) = h\} \quad (4)$$

is an invariant manifold for the system. Therefore, the system has an infinite family of invariant manifolds foliating the whole \mathbb{R}^3 , and so the dynamics is essentially two-dimensional.

Theorem

Consider system (1) with function W defined as in (2). If $a_{12} \neq 0$, then on each invariant set S_h given in (4), the dynamics is topologically equivalent to the Liénard system

$$\dot{X} = Y - F(X), \quad \dot{Y} = -g(X) + h, \quad (5)$$

where F and g are given by

$$F(X) = -a_{11}q(X) - a_{22}X, \quad g(X) = a_{11}a_{22}q(X) - a_{12}a_{21}X. \quad (6)$$

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Moreover, $(X(\tau), Y(\tau)) \in \mathbb{R}^2$ is a solution of the Liénard system (5) for a given $h \in \mathbb{R}$, if and only if $E_h(X(\tau), Y(\tau)) \in \mathbb{R}^3$ is a solution of system (1) on S_h , where

$$E_h(X(\tau), Y(\tau)) = \begin{pmatrix} Y(\tau) - F(X(\tau)) \\ \frac{1}{a_{12}} [(a_{22}^2 + a_{12}a_{21})Y(\tau) - a_{22}Y(\tau) + h] \\ X(\tau) \end{pmatrix}. \quad (7)$$

3D PWL Memristor Oscillator

Here

$$q(z) = \begin{cases} b(z-1) + a, & \text{if } z > 1, \\ az, & \text{if } |z| \leq 1, \\ b(z+1) - a, & \text{if } z < -1, \end{cases} \quad (8)$$

so that

$$W(z) = \begin{cases} b, & \text{if } |z| > 1, \\ a, & \text{if } |z| \leq 1, \end{cases} \quad \text{with } a \neq b. \quad (9)$$

We define the auxiliary matrices

$$A_E = \begin{pmatrix} b \cdot a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}, \quad A_C = \begin{pmatrix} a \cdot a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}, \quad (10)$$

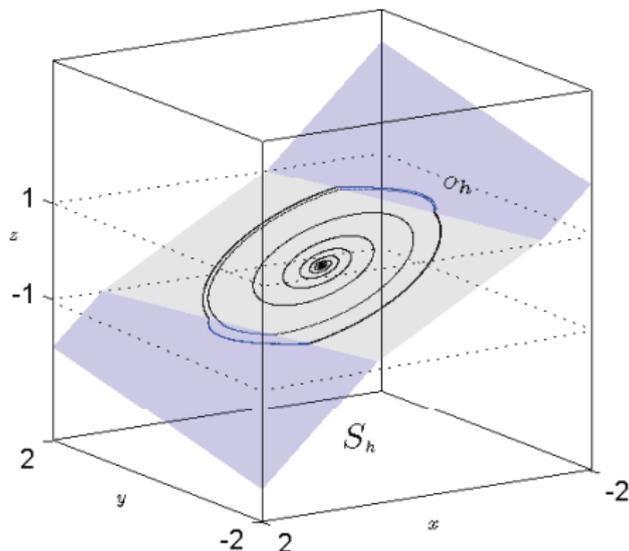
and the traces and determinants of such matrices

$$\begin{aligned} t_E &= b a_{11} + a_{22}, & t_C &= a a_{11} + a_{22}, \\ d_E &= b a_{11} a_{22} - a_{12} a_{21}, & d_C &= a a_{11} a_{22} - a_{12} a_{21}. \end{aligned} \quad (11)$$

3D PWL Memristor Oscillator

From Theorem 2, we obtain the piecewise linear invariant manifolds S_h defined by

$$S_h = \begin{cases} a_{12}y - a_{22}x + d_E z = h - a_{22}(t_C - t_E), & \text{if } z > 1, \\ a_{12}y - a_{22}x + d_C z = h, & \text{if } |z| \leq 1, \\ a_{12}y - a_{22}x + d_E z = h - a_{22}(t_E - t_C), & \text{if } z < -1, \end{cases} \quad (12)$$



Theorem

Consider the function W defined as in (9). If $a_{12} \neq 0$, then on each invariant set S_h of system (1), the dynamics is topologically equivalent to the continuous Liénard system

$$\dot{X} = F(X) - Y, \quad \dot{Y} = g(X) - h, \quad (13)$$

where F and g are given by

$$F(X) = \begin{cases} t_E(X-1) + t_C, & \text{if } X > 1, \\ t_C X, & \text{if } |X| \leq 1, \\ t_E(X+1) - t_C, & \text{if } X < -1, \end{cases} \quad (14)$$

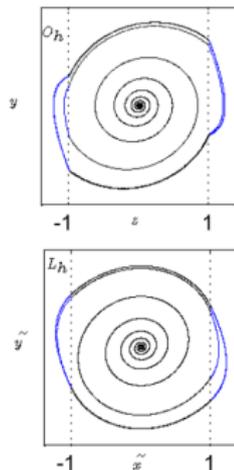
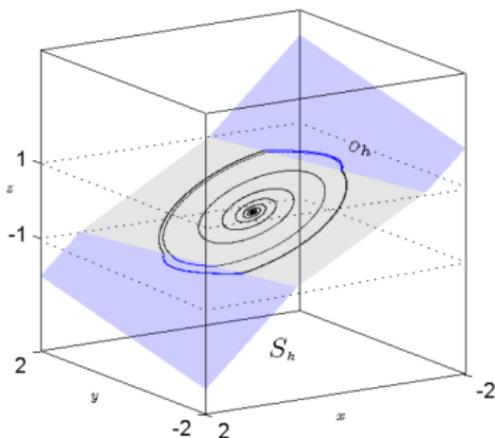
$$g(X) = \begin{cases} d_E(X-1) + d_C, & \text{if } X > 1, \\ d_C X, & \text{if } |X| \leq 1, \\ d_E(X+1) - d_C, & \text{if } X < -1, \end{cases} \quad (15)$$

and t_E, t_C, d_E, d_C are the traces and determinants (11) of the matrices defined in (10).

Moreover, $(X(\tau), Y(\tau)) \in \mathbb{R}^2$ is a solution of the continuous reduced system (13) for a given $h \in \mathbb{R}$, if and only if $E_h(X(\tau), Y(\tau)) \in \mathbb{R}^3$ is a solution of system (1) on S_h , where

$$E_h(X(\tau), Y(\tau)) = \begin{pmatrix} F(X(\tau), Y(\tau)) - Y(\tau) \\ \frac{1}{a_{12}} [(a_{22}^2 + a_{12}a_{21})X(\tau) - a_{22}Y(\tau) + h] \\ X(\tau) \end{pmatrix}, \quad (16)$$

and the function F is defined as in (14).



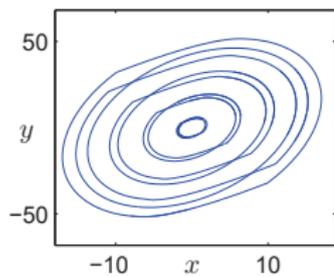
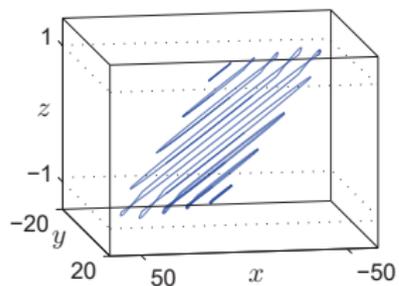
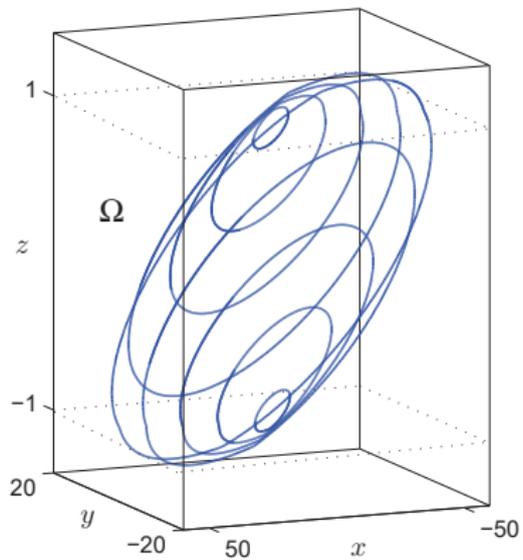
Theorem

Consider system (1)-(9) with $a \neq b$, and parameters such that

$$t_E < 0, \quad t_C > 0, \quad d_E, d_C > 0, \quad (17)$$

where t_E, t_C, d_E and d_C are the traces and determinants of matrices defined in (10). Then for any $|h| < d_C$ the system has an infinite number of stable periodic orbits, each one of them contained in the set S_h defined in (12),

Moreover, such periodic orbits generate a tubular surface Ω which is homeomorphic to the cylinder $\mathbf{S}^1 \times (-1, 1)$, and symmetric with respect to the origin.



Cubic Memristor Oscillator

Theorem

Consider system (1) with the functions q and W defined by

$$\begin{aligned}q(z) &= cz^3 + az^2 + bz, \\W(z) &= q'(z) = 3cz^2 + 2az + b.\end{aligned}\tag{18}$$

Cubic Memristor Oscillator

Theorem

Consider system (1) with the functions q and W defined by

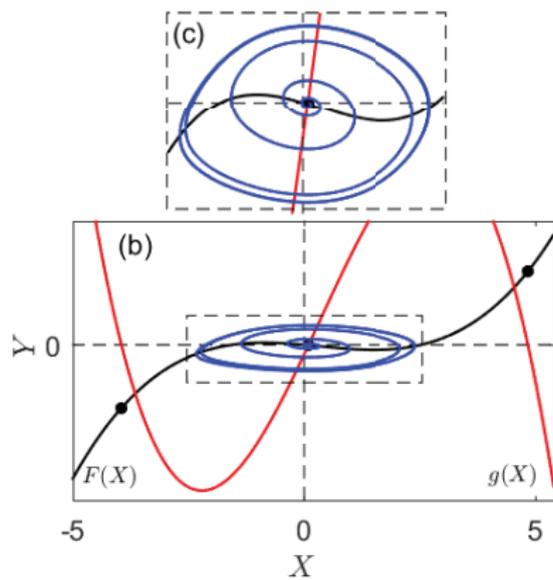
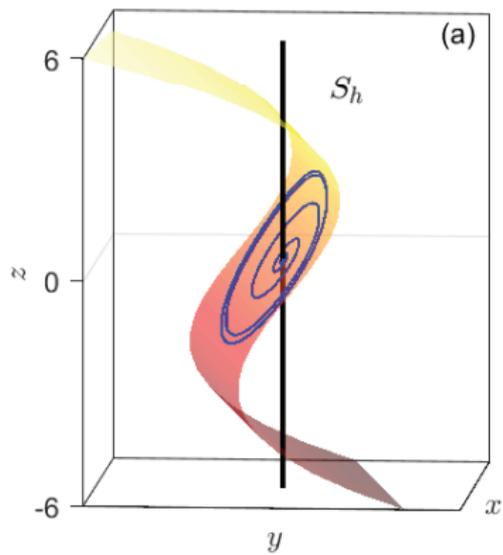
$$\begin{aligned}q(z) &= cz^3 + az^2 + bz, \\W(z) &= q'(z) = 3cz^2 + 2az + b.\end{aligned}\tag{18}$$

If $a_{12} \neq 0$, then on each invariant set S_h given by

$$\begin{aligned}S_h = \{(x, y, z) \in \mathbb{R}^3 : &-a_{22}x + a_{12}y + a_{11}a_{22}cz^3 + \\&+ aa_{11}a_{22}z^2 + (ba_{11}a_{22} - a_{12}a_{21})z = h\}\end{aligned}\tag{19}$$

the dynamics is topologically equivalent to the Liénard system

$$\begin{aligned}\dot{x} &= y + ca_{11}x^3 + aa_{11}x^2 + (ba_{11} + a_{22})x, \\ \dot{y} &= -a_{11}a_{22}cx^3 - a_{11}a_{22}ax^2 + (a_{12}a_{21} - a_{11}a_{22}b)x + h.\end{aligned}\tag{20}$$

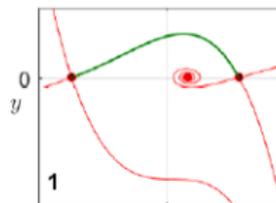
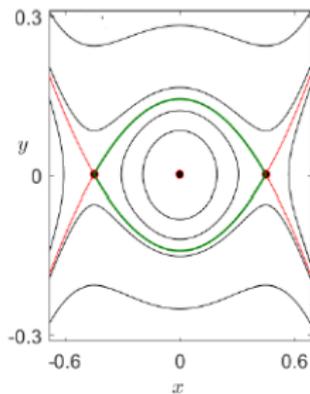


Moreover, if $a_{11}a_{22} < 0$ then the system can be written into the form

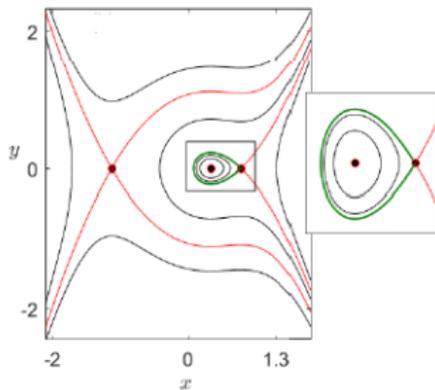
$$\begin{aligned}\dot{x} &= y, \\ \dot{y} &= \mu_1 + \mu_2 x + cx^3 + y(\mu_3 + 3ca_{11}x^2),\end{aligned}\tag{21}$$

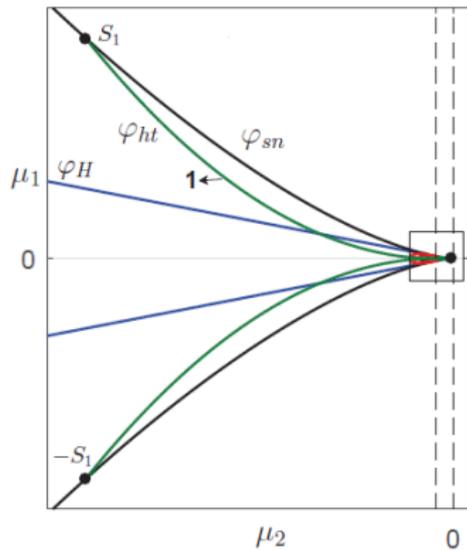
where the new parameters μ_1, μ_2 and μ_3 are

$$\begin{aligned}\mu_1 &= \frac{27ch + a_{11}a_{22}a(9cb - 2a^2) - 9caa_{12}a_{21}}{27c^2(-a_{11}a_{22})^{5/2}}, \\ \mu_2 &= \frac{a_{11}a_{22}(a^2 - 3cb) + 3ca_{12}a_{21}}{3c(a_{11}a_{22})^2}, \quad \mu_3 = \frac{a_{11}(a^2 - 3cb) - 3ca_{22}}{3ca_{11}a_{22}}.\end{aligned}$$



$$\begin{aligned} \dot{x} &= y, \\ \dot{y} &= \mu_1 + \mu_2 x + x^3 + y(\mu_3 - 3x^2), \end{aligned}$$





$$\varphi_{sn} = \{(\mu_1, \mu_2, \mu_3) : 27\mu_1^2 + 4\mu_2^3 = 0 \text{ and } \mu_3 \in \mathbb{R}\},$$

$$\varphi_H = \{(\mu_1, \mu_2, \mu_3) : \mu_1 = \mp \left(\frac{\mu_3}{3}\right)^{3/2} \mp \left(\frac{\mu_3}{3}\right)^{1/2} \mu_2, \mu_2 < -\mu_3\},$$

Melnikov theory for $\mu_3 > 0$

$$\varphi_h = \{(\mu_2, \mu_1) \in \mathbb{R}^2 : \mu_1 = \mu_3 \nu_2(\theta), \quad \mu_2 = \pm \mu_3^{3/2} \nu_1(\theta), \quad 0 < \theta < \infty\},$$

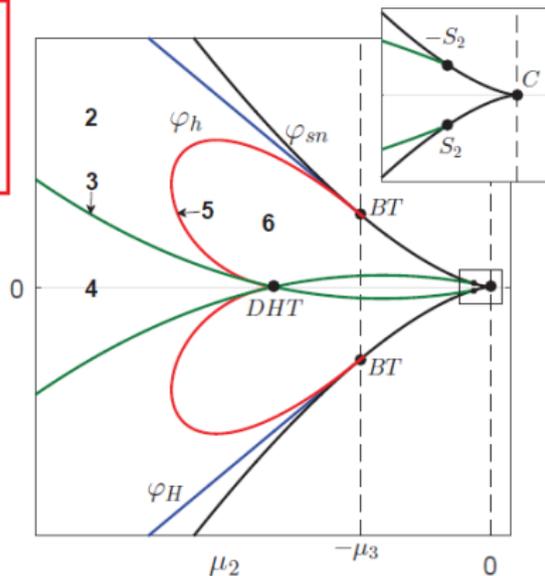
$$\nu_2(\theta) = \frac{-10(\cosh 2\theta + 5)(9 \sinh \theta + \sinh 3\theta - 12\theta \cosh \theta)}{3(370 \sinh \theta + 115 \sinh 3\theta + \sinh 5\theta - 60\theta(11 \cosh \theta + \cosh 3\theta))},$$

$$\nu_1(\theta) = -(\nu_2(\theta) s + s^3), \quad s^2 = \frac{-\cosh^2 \theta}{2 + \cosh^2 \theta} \nu_2(\theta).$$

$$\varphi_{ht} = \{(\mu_2, \mu_1) \in \mathbb{R}^2 : \mu_1 = \pm \frac{\sqrt{2}}{15} \mu_2 (3\mu_2 + 5\mu_3), \quad \mu_2 < -\frac{5}{3} \mu_3\}.$$

$$DHT \equiv (0, -5\mu_3/3).$$

$$BT_{\pm} \equiv \left(-\mu_3, \pm \frac{2}{3} \sqrt{\frac{\mu_3^3}{3}}\right).$$



Application to a cubic memristor

Theorem

Consider the cubic memristor with $(a^2 - 3b + 3\beta)/(3\beta) > 0$ sufficiently small, and suppose that $0 < 3b - a^2 < 3\xi/\beta$.

Then there exists $K < 0$ with $K < (-5/3)(a^2 - 3b + 3\beta) < 0$, such that the system has an infinite number of stable periodic orbits; in particular, for any initial condition $(x_0, y_0, z_0) \in \mathbb{R}^3$ with $x_0 \neq 0$ or $y_0 \neq 0$ and

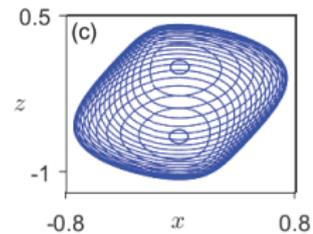
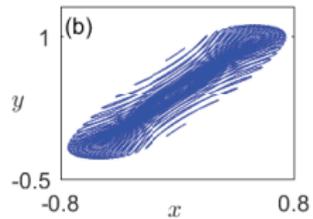
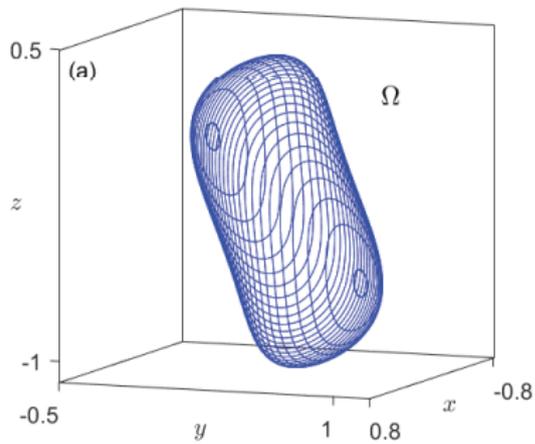
$$\min\{A, B\} < -\beta x_0 - \xi y_0 + \xi z_0 - \beta q(z_0) < \max\{A, B\},$$

where

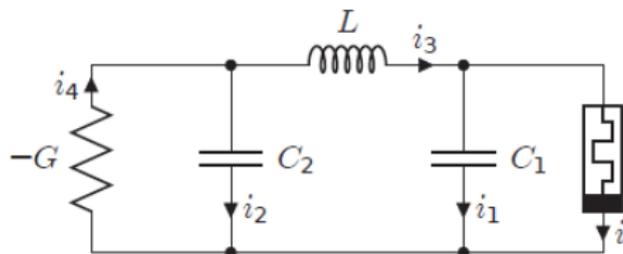
$$A = \frac{1}{27} \left(a - \sqrt{a^2 - 3b + 3\beta} \right) \left(6b\beta - 9\xi + 3\beta^2 - a^2\beta + a\beta \sqrt{a^2 - 3b + 3\beta} \right)$$

$$B = -\frac{1}{27} \left(a + \sqrt{a^2 - 3b + 3\beta} \right) \left(9\xi - 6b\beta - 3\beta^2 + a^2\beta + a\beta \sqrt{a^2 - 3b + 3\beta} \right),$$

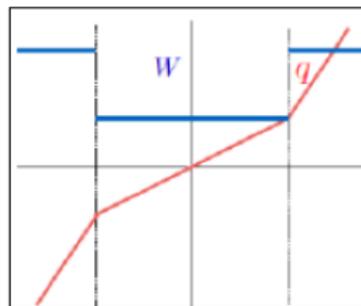
the steady state solution is periodic. Moreover, the periodic orbits generate a topological sphere Ω foliated by such periodic orbits.

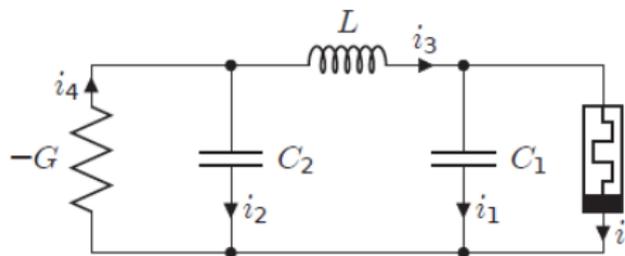


Application to a 4D memristor oscillator

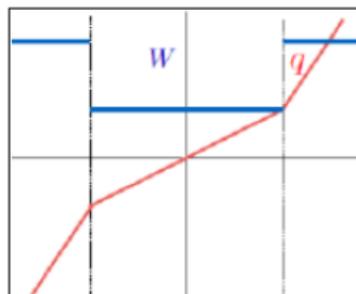


$$\begin{aligned}\frac{dx}{d\tau} &= \alpha y - \alpha W(w)x, \\ \frac{dy}{d\tau} &= z - x, \\ \frac{dz}{d\tau} &= -\beta y + \gamma z, \\ \frac{dw}{d\tau} &= x,\end{aligned}$$





$$\begin{aligned} \frac{dx}{d\tau} &= \alpha y - \alpha W(w)x, \\ \frac{dy}{d\tau} &= z - x, \\ \frac{dz}{d\tau} &= -\beta y + \gamma z, \\ \frac{dw}{d\tau} &= x, \end{aligned}$$



$$\begin{aligned} \dot{y}_1 &= y_4, \\ \dot{y}_2 &= y_3 - y_4, \\ \dot{y}_3 &= -\beta y_2 + \gamma y_3, \\ \dot{y}_4 &= y_2 - W(y_1)y_4, \end{aligned}$$

$$\dot{y}_1 = y_4,$$

$$\dot{y}_2 = y_3 - y_4,$$

$$\dot{y}_3 = -\beta y_2 + \gamma y_3,$$

$$\dot{y}_4 = y_2 - W(y_1)y_4,$$

$$H(y_1, y_2, y_3, y_4) = \beta(y_4 + q(y_1)) - \gamma(y_1 + y_2) + y_3,$$

$$S_h = \{(y_1, y_2, y_3, y_4) \in \mathbb{R}^4 : H(y_1, y_2, y_3, y_4) = h\}.$$

$$\begin{aligned}\dot{x}_1 &= \frac{\gamma}{\beta}(x_1 + x_2) - q(x_1) - \frac{1}{\beta}x_3 + \frac{h}{\beta}, \\ \dot{x}_2 &= x_3 - \frac{\gamma}{\beta}(x_1 + x_2) + q(x_1) + \frac{1}{\beta}x_3 - \frac{h}{\beta}, \\ \dot{x}_3 &= -\beta x_2 + \gamma x_3.\end{aligned}$$

$$\begin{aligned}\dot{x}_1 &= \frac{\gamma}{\beta}(x_1 + x_2) - q(x_1) - \frac{1}{\beta}x_3 + \frac{h}{\beta}, \\ \dot{x}_2 &= x_3 - \frac{\gamma}{\beta}(x_1 + x_2) + q(x_1) + \frac{1}{\beta}x_3 - \frac{h}{\beta}, \\ \dot{x}_3 &= -\beta x_2 + \gamma x_3.\end{aligned}$$

$$A_C = \frac{1}{\beta} \begin{pmatrix} \gamma - a\beta & \gamma & -1 \\ a\beta - \gamma & -\gamma & 1 + \beta \\ 0 & -\beta^2 & \gamma\beta \end{pmatrix},$$

$$A_E = \frac{1}{\beta} \begin{pmatrix} \gamma - b\beta & \gamma & -1 \\ b\beta - \gamma & -\gamma & 1 + \beta \\ 0 & -\beta^2 & \gamma\beta \end{pmatrix},$$

$$\dot{\mathbf{x}} = \begin{pmatrix} t_E & -1 & 0 \\ m_E & 0 & -1 \\ d_E & 0 & 0 \end{pmatrix} \mathbf{x} + \begin{pmatrix} t_C - t_E \\ m_C - m_E \\ d_C - d_E \end{pmatrix} \text{sat}(\mathbf{e}_1^T \mathbf{x}) + \frac{h}{\beta} \begin{pmatrix} 1 \\ \gamma \\ \beta \end{pmatrix}$$

$$\dot{\mathbf{x}} = \begin{pmatrix} t_E & -1 & 0 \\ m_E & 0 & -1 \\ d_E & 0 & 0 \end{pmatrix} \mathbf{x} + \begin{pmatrix} t_C - t_E \\ m_C - m_E \\ d_C - d_E \end{pmatrix} \text{sat}(\mathbf{e}_1^T \mathbf{x}) + \frac{h}{\beta} \begin{pmatrix} 1 \\ \gamma \\ \beta \end{pmatrix}$$

$h \in \mathbb{R}$ and $\beta \neq 0$, $(x_1(\tau), x_2(\tau), x_3(\tau)) \in \mathbb{R}^3$

$$\mathbf{y}(\tau) = \begin{pmatrix} x_1(\tau) \\ (\gamma^2 - \beta - 1)x_1(\tau) - \gamma x_2(\tau) + x_3(\tau) \\ (\gamma^3 - 2\beta\gamma)x_1(\tau) + (\beta - \gamma^2)x_2(\tau) + \gamma x_3(\tau) \\ \gamma x_1(\tau) - x_2(\tau) - q(x_1(\tau)) + h/\beta \end{pmatrix}$$

Theorem

Take $m_C > 0$, $\varepsilon = m_C t_C - d_C$, and assume the non-degeneracy condition

$$\rho = d_C m_C - d_C m_E + d_E m_C - m_C^2 t_E \neq 0.$$

Then, for $\varepsilon = 0$ the 4D system undergoes a focus-center-limit cycle bifurcation simultaneously on all the levels S_h with $|h| < |d_C| \neq 0$.

Thus, from the lineal center configurations in the central zone, which exist for $\varepsilon = 0$, an infinite number of stable periodic orbits simultaneously appears for $\varepsilon \rho > 0$ and ε sufficiently small.

Theorem

Take $m_C > 0$, $\varepsilon = m_C t_C - d_C$, and assume the non-degeneracy condition

$$\rho = d_C m_C - d_C m_E + d_E m_C - m_C^2 t_E \neq 0.$$

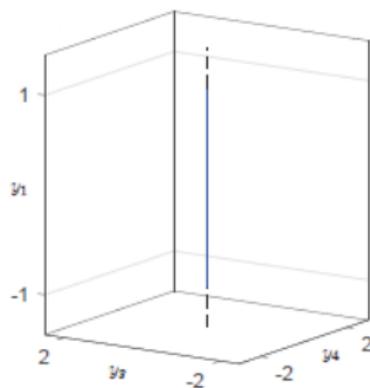
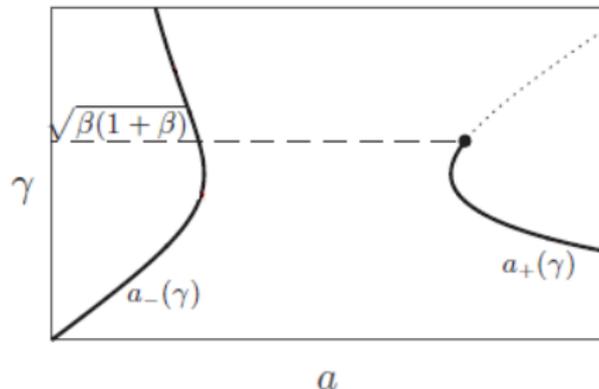
Then, for $\varepsilon = 0$ the 4D system undergoes a focus-center-limit cycle bifurcation simultaneously on all the levels S_h with $|h| < |d_C| \neq 0$.

In particular, if $\rho > 0$ and $d_C < 0$, then the periodic orbits bifurcates for $\varepsilon > 0$ and are orbitally asymptotically stable. Otherwise, the bifurcating periodic orbits are unstable.

MFCC bifurcation

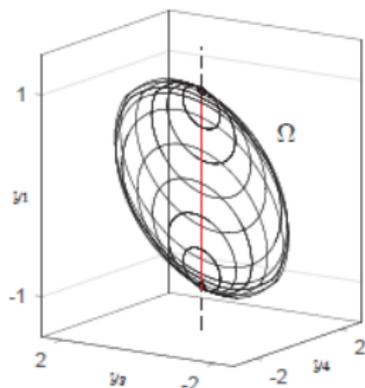
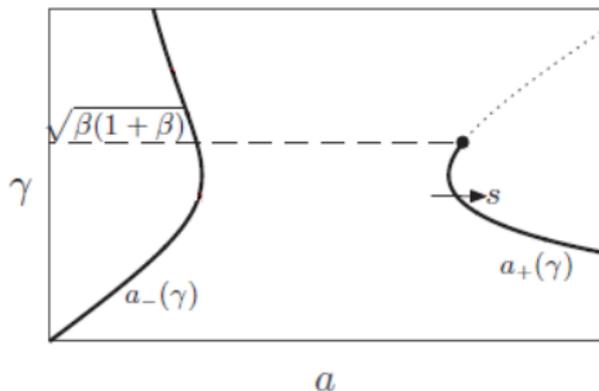
$$a_{\pm}(\gamma) = \frac{\gamma^2 + 1}{2\gamma} \pm \sqrt{\left(\frac{\gamma^2 + 1}{2\gamma}\right)^2 - \beta},$$

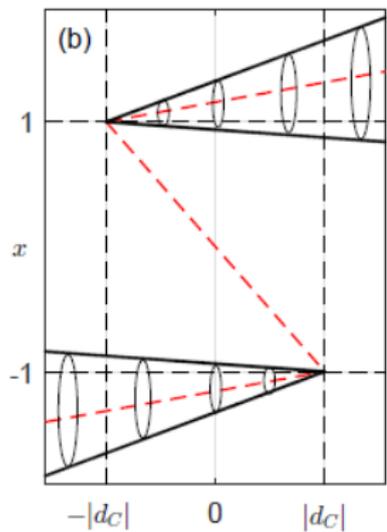
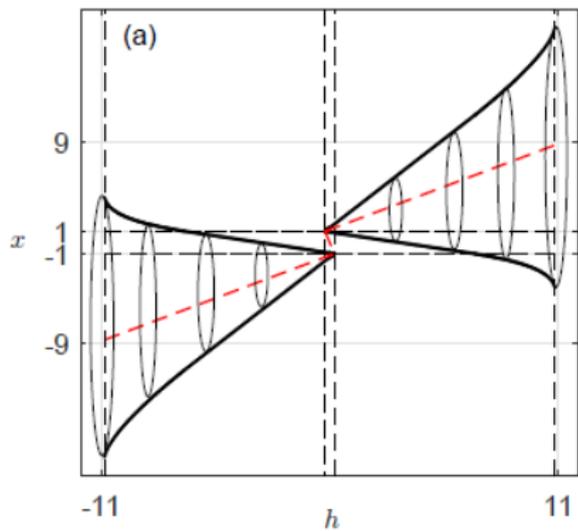
If $0 < \beta < 1$, $\gamma < \sqrt{\beta(1+\beta)}$ and $0 < b < a$ then for $a = a_+(\gamma)$ the system undergoes a MFCC bifurcation, so that when $a \leq a_+(\gamma)$ all the equilibria in central segment are stable, becoming unstable for $a > a_+(\gamma)$.



MFCC bifurcation

For $a - a_+(\gamma) > 0$ and sufficiently small, there appears a bounded hypersurface $\Omega \subset \mathbb{R}^4$ foliated by stable periodic orbits.





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- On Discontinuous Piecewise Linear Models for Memristor Oscillators, *International Journal of Bifurcation and Chaos*. DOI: 10.1142/s0218127417300221.
- Unravelling the dynamical richness of 3D canonical memristor oscillators, *Microelectronic Engineering*. DOI:10.1016/j.mee.2017.08.004.
- Bifurcation set of a Bogdanov-Takens system with symmetry. Application to 3D cubic Memristor oscillators, *Submitted* .
- A multiple focus-center-cycle bifurcation in 4D discontinuous piecewise linear Memristor oscillators, *Nonlinear Dynamics*. DOI: 10.1007/s11071-018-4541-2.

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$$\dot{\mathbf{x}} = \mathbf{F}(\mathbf{x}) = \begin{cases} \mathbf{A}\mathbf{x} + \mathbf{b}_L, & \text{if } \mathbf{e}_1^T \mathbf{x} \leq 0, \\ \mathbf{A}\mathbf{x} + \mathbf{b}_R, & \text{if } \mathbf{e}_1^T \mathbf{x} > 0, \end{cases} \quad (22)$$

where matrix A and vectors $\mathbf{b}_{\{L,R\}}$ are

$$A = \begin{pmatrix} -ca_0 & a_0c^2 - a_1c + 1 \\ -a_0 & ca_0 - a_1 \end{pmatrix}, \quad \mathbf{b}_R = \begin{pmatrix} bkc - ca_0y_c \\ bk - a_0y_c \end{pmatrix}, \quad \mathbf{b}_L = \begin{pmatrix} -bkc - ca_0y_c \\ -bk - a_0y_c \end{pmatrix},$$

and \mathbf{e}_1 is the first canonical vector.

Stroboscopic map

For $|A| = a_0 \neq 0$, a fixed $t > 0$ and taking into account the solutions of each vector field, the stroboscopic map is defined by

$$P(\mathbf{x}; t) = \begin{cases} e^{At}\mathbf{x} + (e^{At} - I)A^{-1}\mathbf{b}_L, & \text{if } \mathbf{e}_1^T \mathbf{x} \leq 0, \\ e^{At}\mathbf{x} + (e^{At} - I)A^{-1}\mathbf{b}_R, & \text{if } \mathbf{e}_1^T \mathbf{x} > 0, \end{cases} \quad (23)$$

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If $b_{ck} \neq 0$ the map is discontinuous, and always has two fixed points given by

$$\mathbf{x}_{\{L,R\}}^* = -A^{-1}\mathbf{b}_{\{L,R\}}$$

Big Bang Bifurcation

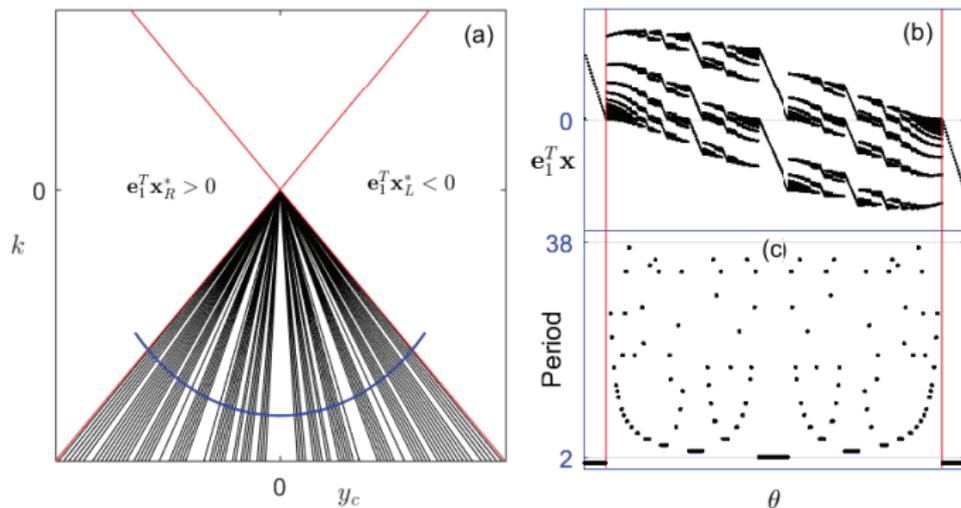


Figure: $t = 0.1$, $a_0 = -2$, $a_1 = -5$, $b = -1$ and $c = 1.5$.

Big Bang Bifurcation

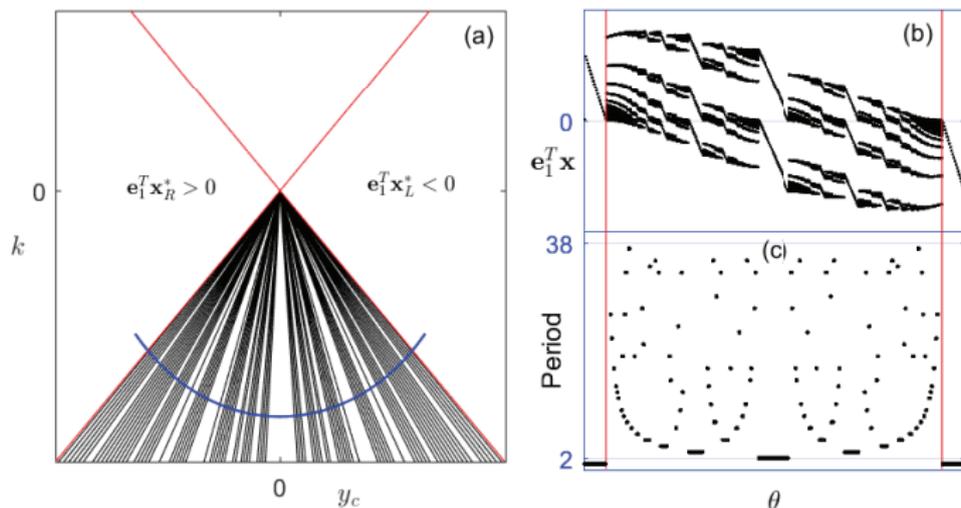


Figure: $t = 0.1$, $a_0 = -2$, $a_1 = -5$, $b = -1$ and $c = 1.5$.

They conjectured that when the eigenvalues of the matrix e^{At} are real and lower than 1, both fixed points are virtual and the sliding set is attractive, then the stroboscopic map has a BB bifurcation point at $(y_c, k) = (0, 0)$.

Consider the planar piecewise linear system

$$\dot{\mathbf{x}} = \begin{cases} A_- \mathbf{x} + \mathbf{b}_-, & \text{if } \mathbf{e}_1^T \mathbf{x} \leq 0, \\ A_+ \mathbf{x} + \mathbf{b}_+, & \text{if } \mathbf{e}_1^T \mathbf{x} > 0, \end{cases} \quad (24)$$

where $A_{\pm} = (a_{ij}^{\pm})$ are constant matrices of order 2. If we consider the modal parameter $m_{\{L,R\}} \in \{0, 1, i\}$ defined in each zone by

$$m_{\{L,R\}} = \begin{cases} i, & \text{if } t_{\mp}^2 - 4d_{\mp} < 0, \\ 0, & \text{if } t_{\mp}^2 - 4d_{\mp} = 0, \\ 1 & \text{if } t_{\mp}^2 - 4d_{\mp} > 0. \end{cases}$$

where i is the unit imaginary.

Then the system can be written into the normalized canonical form defined by

$$\dot{\mathbf{x}} = \begin{cases} A_L \mathbf{x} - \mathbf{b}_L, & \text{if } \mathbf{e}_1^T \mathbf{x} \leq 0, \\ A_R \mathbf{x} - \mathbf{b}_R, & \text{if } \mathbf{e}_1^T \mathbf{x} > 0, \end{cases} \quad (25)$$

where

$$A_j = \begin{pmatrix} 2\gamma_j & -1 \\ \gamma_j^2 - m_j^2 & 0 \end{pmatrix}, \quad \mathbf{b}_R = \begin{pmatrix} -b \\ a_R \end{pmatrix}, \quad \mathbf{b}_L = \begin{pmatrix} 0 \\ a_L \end{pmatrix}, \quad j = \{L, R\}. \quad (26)$$

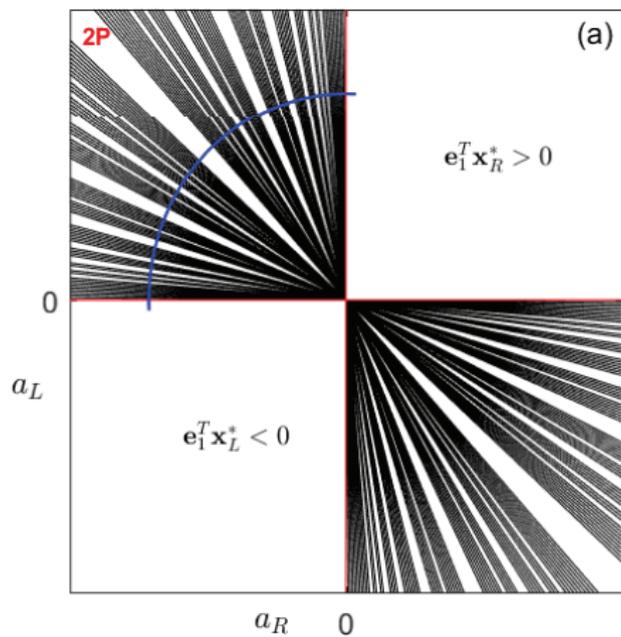
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The stroboscopic map when $A_L = A_R$

Given $m \in \{0, 1, i\}$ and a fixed value $t > 0$, the stroboscopic map P is defined by

$$P(\mathbf{x}; t) = \begin{cases} P_L(\mathbf{x}; t) = e^{At}\mathbf{x} - (\Phi - I)A^{-1}\mathbf{b}_L, & \text{if } \mathbf{e}_1^T \mathbf{x} \leq 0, \\ P_R(\mathbf{x}; t) = e^{At}\mathbf{x} - (\Phi - I)A^{-1}\mathbf{b}_R, & \text{if } \mathbf{e}_1^T \mathbf{x} > 0, \end{cases}$$

where the matrix A is defined as in (26).



To alleviate notation, we define the auxiliary functions

$$C_k = \begin{cases} \cosh(kt), & \text{if } m = 1, \\ \cos(kt), & \text{if } m = i, \\ 1, & \text{if } m = 0, \end{cases}, \quad S_k = \begin{cases} \sinh(kt), & \text{if } m = 1, \\ \sin(kt), & \text{if } m = i, \\ kt, & \text{if } m = 0. \end{cases}$$

and for $k \geq 1$, and $m \in \{0, 1, i\}$,

$$\mu_k^\pm := C_k \pm \gamma S_k.$$

Theorem

Given $m \in \{0, 1, i\}$, $0 < t < 1$, $\gamma \in \mathbb{R}$ such that $D = \gamma^2 - m^2 > 0$ and $\gamma < 0$, consider the functions

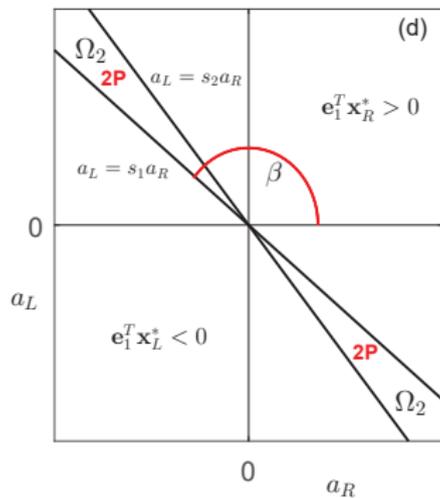
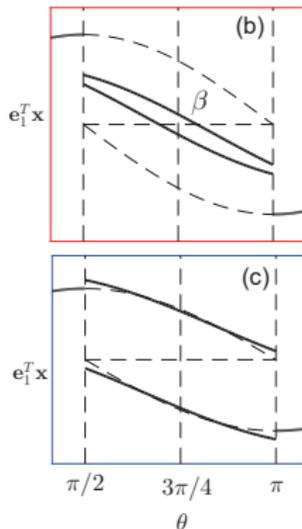
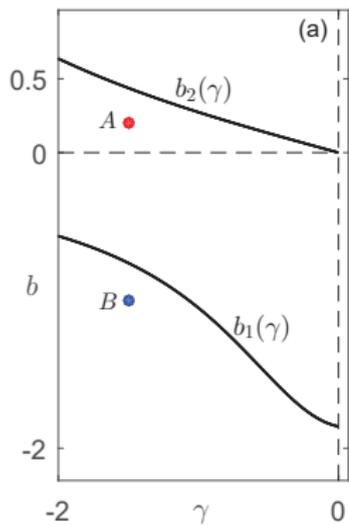
$$h_2^{(1)}(\gamma) = \frac{e^{4t\gamma} - e^{3t\gamma}\mu_1^+ - e^{2t\gamma}\mu_2^- + e^{t\gamma}\mu_1^-}{1 + e^{4t\gamma} - 2C_2 e^{2t\gamma}},$$

$$r_2^{(1)}(\gamma) = \frac{e^{2t\gamma}S_2 - (e^{3t\gamma} + e^{t\gamma})S_1}{1 + e^{4t\gamma} - 2C_2 e^{2t\gamma}},$$

and

$$b_1(\gamma) = \frac{h_2^{(1)}(\gamma)}{r_2^{(1)}(\gamma)D}, \quad b_2(\gamma) = \frac{2h_2^{(1)}(\gamma) - 1}{\sqrt{2}r_2^{(1)}(\gamma)D}.$$

The following statements hold for map P .



(a) For all $b \in \mathbb{R}$ with $b_1(\gamma) < b < b_2(\gamma)$ there exists a unique $\beta \in (3\pi/4, \pi)$ defined by

$$\beta = \arcsin \left(\frac{-br_2^{(1)}(\gamma)D}{\sqrt{(1-h_2^{(1)}(\gamma))^2 + (h_2^{(1)}(\gamma))^2}} \right) - \pi - \arctan \left(\frac{h_2^{(1)}(\gamma)}{1-h_2^{(1)}(\gamma)} \right),$$

such that for all $(a_R, a_L) \in \Omega_2$ map P has a unique stable 2-periodic orbit, where

$$\Omega_2 = \{(a_R, a_L) \in \mathbb{R}^2 : s_2 a_R < a_L < s_1 a_R, \quad s_1 a_R < a_L < s_2 a_R\},$$

with $s_1 = \tan(\beta)$ and $s_2 = 1/s_1$.

- (a) For all $b \in \mathbb{R}$ with $b_1(\gamma) < b < b_2(\gamma)$ there exists a unique $\beta \in (3\pi/4, \pi)$ defined by

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with $s_1 = \tan(\beta)$ and $s_2 = 1/s_1$.

- (b) For all $b \in \mathbb{R}$ with $b \leq b_1(\gamma)$ map P has a unique stable 2-periodic orbit for all $a_R, a_L \in \mathbb{R}$ with $a_R \cdot a_L < 0$.

Big Bang Bifurcation

Conjecture

Given $m \in \{0, 1\}$ and $0 < t < 1$. Consider the two-parameter plane (a_R, a_L) , and the functions

$$h_3^{(2)}(\gamma, t) = \frac{e^{4t\gamma}\mu_2^+ - e^{3t\gamma}\mu_3^+ - e^{t\gamma}\mu_1^- + 1}{e^{6t\gamma} - 2C_3e^{3t\gamma} + 1},$$

$$r_3^{(2)}(\gamma, t) = \frac{e^{4t\gamma}S_2 - e^{3t\gamma}S_3 + e^{t\gamma}S_1}{e^{6t\gamma} - 2C_3e^{3t\gamma} + 1}.$$

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Then for $\gamma + m < 0$ sufficiently small and

$$b = \min \left\{ \frac{1}{\gamma + m}, F(\gamma, t) \right\},$$

where F is defined by

$$F(\gamma, t) = \frac{1}{\gamma^2 - m^2} \frac{2h_3^{(2)}(\gamma, t) - 1}{\sqrt{2}r_3^{(2)}(\gamma, t)},$$

the stroboscopic map P has at $(0, 0)$ a big bang bifurcation point of codimension two.

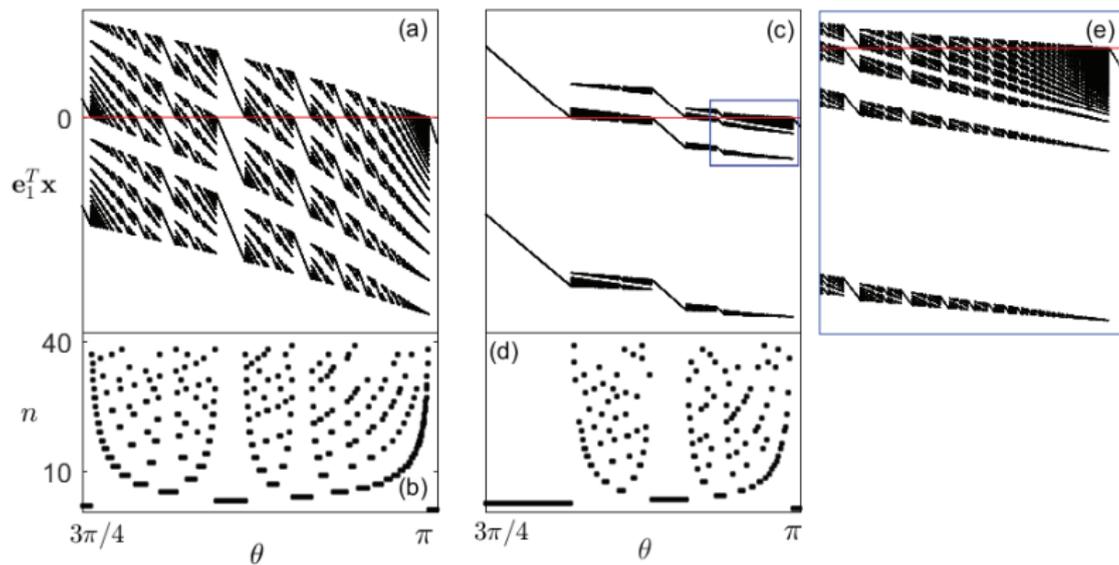


Figure: (a) $m = 0, t = 0.9, \gamma = -0.2$ and $b = 1/\gamma$. (c) $m = 1, t = 0.9, \gamma = -1.05$ and $b = F(\gamma, t) \approx -9.27$.

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- On the Big Bang Bifurcation in the stroboscopic map for discontinuous PWL systems. An application in Discretized Sliding-mode Control Systems. *In preparation.*

!!! Thanks for your attention !!!



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